

# AT54 EXAMEN FINAL

27 juin 2010 de 10h15 à 12h15 en salle P227 à Sévenans

**You can answer either in English or in French**  
**No documents or PC's allowed. Mobile phones must be TURNED OFF**  
**Write clearly and avoid erasures**

## PART1: SIGNAL PROCESSING

### EXERCISE 1 (3 POINTS)

Consider the following LTI system, whose Z-transform of the impulse response is:

$$H(z) = \frac{(1 - z^{-1})}{(1 - 2z^{-1})(1 - 5z^{-1})} \quad |z| < 2$$

Compute :

- $h(n)$ , that is the impulse response
- The corresponding difference equation if  $x[n]$  is the input sequence and  $y[n]$  the output sequence.
- Is the system stable ? Is it causal ? Why?
- Compute the output  $y(n)$  if a unit step function is given (considering null initial conditions). Make the computation by using BOTH the Z-transform AND the convolution product, and verify that the result is the same.

(Hint:  $\sum_{k=-\infty}^n a^k = \frac{a^{n+1}}{a-1}$  if  $|a| > 1$  ... why ?)

### EXERCISE 2 (3 POINTS) (Theory and practice)

Define the DFT computed on N-points, by using the notion of DFS. Then consider the following finite-length sequence:

$$x[n] = \begin{cases} 1, & 0 \leq n \leq 4 \\ 0 & \text{elsewhere} \end{cases}$$

Compute the 5-point DFT of  $x[n]$ .

## PART2: SYSTEM IDENTIFICATION

### EXERCISE 3 (2 POINTS)

Consider the noise model below

$$v(t) = (1 + a_1 q^{-1} + a_2 q^{-2})^{-1} e(t)$$

where  $e(t)$  is white noise whose variance is equal to  $\lambda$ .

- What kind of system is it ?
- What is the estimator  $\hat{v}(t|t-1)$  ?
- What is the value and the variance of the estimation error  $\varepsilon$ ?

### EXERCISE 4 (2 POINTS) (Theory)

Describe and compare the model structures OE and ARX. Then compute for each of them the minimum variance estimator. Draw a block diagram for each of them to explain their difference. What is the name and the form of the generalized OE?

### EXERCISE 5 (3 POINTS) (Theory)

- Define an ARARMAX system (which is not an ARMAX !)
- Find the minimum variance estimator
- Find the parameter vector, the regressor vector and the corresponding equation

### EXERCISE 6 (3 POINTS)

Consider the following white noise  $e(t)$  :

$e(t)$	-22	-3	0	2	4	5
probability	1/12	1/12	1/4	1/4	1/12	1/4

- Verify that  $e(t)$  is zero mean and compute its variance  
Then, if  $v(t) = H(q)e(t)$ , call  $\hat{v}(t|t-1)$  the minimum variance estimator of  $v(t)$ .
- What is the MAP value of  $v(t)$  given the information  $\hat{v}(t|t-1)$  ?
- What is the probability that  $v(t)$  has a value between  $\hat{v}(t|t-1) - 1$  and  $\hat{v}(t|t-1) + 2$  ?

### EXERCISE 7 (4 POINTS)

The following data pairs are given, which are the measured inputs and outputs of a system described by the function  $y(x) = \alpha_1 3^{\alpha_2 x}$ .

$x_i$	1	2	3	4
$y_i$	$\sqrt{27}$	1	1	81

Determine the parameters  $\alpha_1$  and  $\alpha_2$  so that the function  $y(x)$  approximates the data  $(x_i, y_i)$  in the least-squares sense. (Hint: make a suitable change of variables in order to use the least-squares method).

### USEFUL DOCUMENTATION

$$A(q)y(t) = \frac{B(q)}{F(q)}u(t) + \frac{C(q)}{D(q)}e(t) \quad (4.33)$$

TABLE 4.1 Some Common Black-box SISO Models as Special Cases of (4.33)

Polynomials Used in (4.33)	Name of Model Structure
$B$	FIR (finite impulse response)
$AB$	ARX
$ABC$	ARMAX
$AC$	ARMA
$ABD$	ARARX
$ABCD$	ARARMAX
$BF$	OE (output error)
$BFGD$	BJ (Box-Jenkins)

TABLE 3.1 SOME COMMON z-TRANSFORM PAIRS

Sequence	Transform	ROC
1. $\delta[n]$	1	All $z$
2. $u[n]$	$\frac{1}{1-z^{-1}}$	$ z  > 1$
3. $-u[-n-1]$	$\frac{1}{1-z^{-1}}$	$ z  < 1$
4. $\delta[n-m]$	$z^{-m}$	All $z$ except 0 (if $m > 0$ ) or $\infty$ (if $m < 0$ )
5. $a^n u[n]$	$\frac{1}{1-az^{-1}}$	$ z  >  a $
6. $-a^n u[-n-1]$	$\frac{1}{1-az^{-1}}$	$ z  <  a $
7. $na^n u[n]$	$\frac{az^{-1}}{(1-az^{-1})^2}$	$ z  >  a $
8. $-na^n u[-n-1]$	$\frac{az^{-1}}{(1-az^{-1})^2}$	$ z  <  a $