

08/11/13

①

MEDIAN MQ40 - MQ43

Réponses

1.1

$$\omega = -\frac{V}{a}$$

1.2

$$\{V\}_G = \begin{pmatrix} 0 & V \\ 0 & 0 \\ -\frac{V}{a} & 0 \end{pmatrix}$$

1.3

$$\vec{V}_A = \vec{V}_G + \vec{AG} \wedge \vec{\Omega}$$

$$\vec{V}_A = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

1.4

$$\vec{V}_B = \vec{V}_G + \vec{BG} \wedge \vec{\Omega}$$

$$\vec{V}_B = \begin{pmatrix} -V \\ 0 \\ 0 \end{pmatrix}$$

1.5

$$\vec{V}_P = \vec{V}_G + \vec{PG} \wedge \vec{\Omega}$$

avec $\vec{PG} = \begin{pmatrix} -2a \sin \theta \\ -2a \cos \theta \\ 0 \end{pmatrix}$

$$\vec{V}_P = \begin{pmatrix} V + 2V \sin \theta \\ -2V \cos \theta \\ 0 \end{pmatrix}$$

1.6

$$\theta = -\frac{V}{a} t$$

1.7

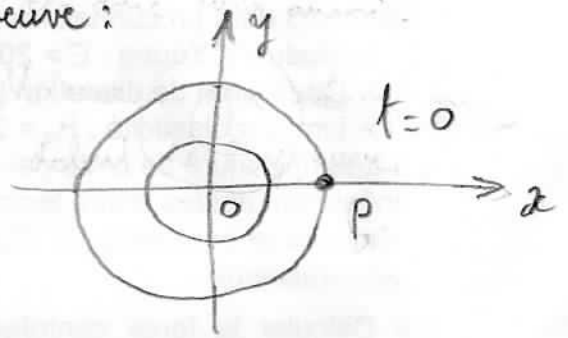
$$\begin{cases} x'(t) = v - 2v \sin \frac{vt}{a} \\ y'(t) = -2v \cos \frac{vt}{a} \end{cases}$$

2

Intégration avec conditions initiales $\begin{cases} x(0) = 2a \\ y(0) = 0 \end{cases}$

L'énoncé ne précise pas que G est en 0 à $t=0$
 Vu au début de l'épreuve :

$$\begin{cases} x(t) = vt + 2a \cos \frac{vt}{a} \\ y(t) = -2a \sin \frac{vt}{a} \end{cases}$$

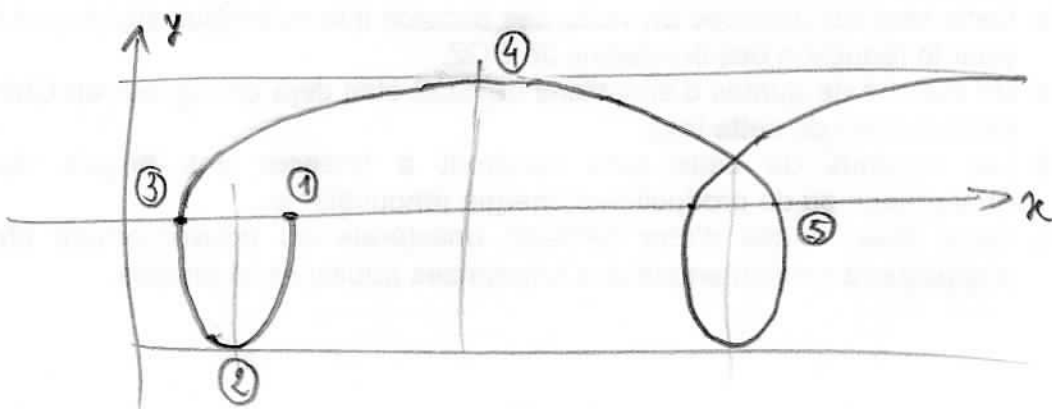


1.8 ① $t=0 \begin{cases} x=2a \\ y=0 \end{cases}$

② $t = \frac{\pi a}{2v} \begin{cases} x = \frac{\pi a}{2} \\ y = -2a \end{cases}$

③ $t = \frac{\pi a}{v} \begin{cases} x = a(\pi - 2) \\ y = 0 \end{cases}$ ④ $t = \frac{3\pi a}{2v} \begin{cases} x = \frac{3\pi a}{2} \\ y = 2a \end{cases}$

⑤ $t = \frac{2\pi a}{v} \begin{cases} x = 2a(\pi + 1) \\ y = 0 \end{cases}$



2.1

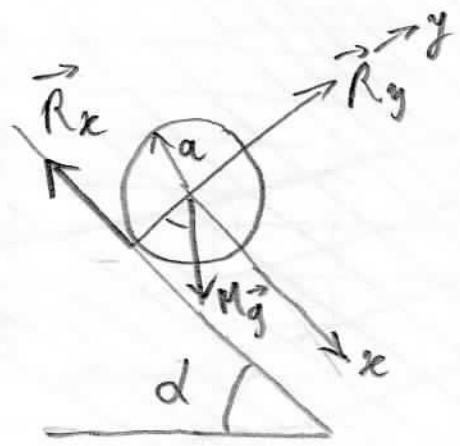
Cylindre plein : $I = \frac{MR^2}{2}$ $I = \frac{\rho \pi L R^4}{2}$

Petit disque : $I_1 = \frac{\rho \pi a^5}{2}$ ($R=L=a$)
 2 grands disques : $I_2 = \frac{32}{2} \rho \pi a^5$ ($R=L=2a$) } $I = \frac{33}{2} \rho \pi a^5$

Masses { Petit disque $m_1 = \rho \pi a^3$
 2 grands disques $m_2 = 8 \rho \pi a^3$ } $M = 9 \rho \pi a^3$
 \downarrow
 $\rho = \frac{M}{9 \pi a^3}$

$I = \frac{11}{6} M a^2$

2.2



$Mg \sin d - R_x = M x''_G$

2.3

$-R_x a = I \theta''$

2.4

$x''_G = -a \theta''$

2.5

2.2 $\rightarrow R_x = M(g \sin d - x''_G)$

2.3 $\rightarrow -M(g \sin d - x''_G) a = I \theta''$

2.1 + 2.4 $\rightarrow -M(g \sin d - x''_G) a = \frac{11}{6} M a^2 \left(-\frac{x''_G}{a}\right)$

$x''_G = \frac{6}{17} g \sin d$

2.6

$$\kappa_G = \frac{3}{17} g \sin \alpha t^2$$

$$\kappa'_G = \frac{6}{17} g \sin \alpha t$$

$$L = \frac{3}{17} g \sin \alpha t_1^2$$

$$t_1 = \sqrt{\frac{17L}{3g \sin \alpha}}$$

2.7

$$V_1 = \kappa'_G(t_1)$$

$$V_1 = \frac{6}{17} g \sin \alpha \sqrt{\frac{17L}{3g \sin \alpha}}$$

$$V_1 = 2 \sqrt{\frac{3g \sin \alpha L}{17}}$$

2.8

$$E_c = \frac{1}{2} M \kappa_G'^2 + \frac{1}{2} I \theta'^2$$

En $\alpha = L$
$$E_c = \frac{1}{2} M V_1^2 \left(1 + \frac{11}{6} a^2 \times \frac{1}{a^2} \right)$$

$$E_c = \frac{17}{12} M V_1^2$$

$$E_c = M g L \sin \alpha$$

Autre solution : $\Delta E_c = \text{travail des poids} = M g L \sin \alpha$
(théorème de l'énergie cinétique)

2.9

Pour le rail $\theta' = -\frac{v}{a}$ et $E_c = \frac{17}{12} M V_1^2$

Pour le plan horizontal : $\theta' = -\frac{v}{2a}$ et $E_c = \frac{1}{2} M V_2^2 \left(1 + \frac{11}{6} a^2 \times \frac{1}{4a^2} \right)$

Conservation de $E_c \rightarrow \frac{17}{12} M V_1^2 = \frac{35}{48} M V_2^2 \rightarrow \frac{V_2^2}{V_1^2} = \frac{4 \times 17}{35}$

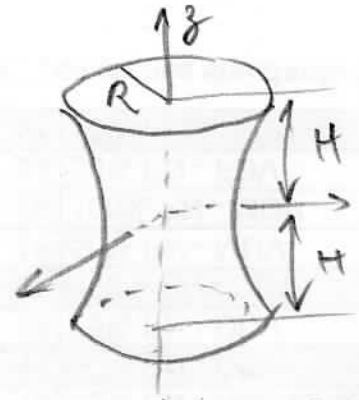
$$\frac{V_2}{V_1} = 139\%$$

Pi l'énergie cinétique est conservée, la roue accélère.

3.1 $r_{max}(z) = R \sqrt{\frac{c^2 + z^2}{c^2 + H^2}}$

$r_{max}(-H) = r_{max}(H) = R$
 $r_{max}(0) = \frac{Rc}{\sqrt{c^2 + H^2}} < R$

3.2



3.3

$c = 0$ $r_{max} = \frac{R|z|}{H}$ - Slide = 2 cônes



3.4

$c \rightarrow +\infty$ $r_{max} \rightarrow R$ Slide \rightarrow cylindre

3.5

$$M = \rho \int_{-H}^H \int_0^{2\pi} \int_0^{r_{max}} r \, dr \, d\theta \, dz$$

$$M = \frac{2\pi\rho R^2 H (3c^2 + H^2)}{3(c^2 + H^2)}$$

$$\rho = \frac{3M(c^2 + H^2)}{2\pi R^2 H (3c^2 + H^2)}$$

3.6

$c = 0$ $M = \frac{2}{3}\pi\rho R^2 H$

Volume en cours ; masse d'un cône = $\frac{1}{3}\pi\rho R^2 H$

$c \rightarrow \infty$ $M \rightarrow 2\pi\rho R^2 H$

masse d'un cylindre

3.7

$$I_3 = \rho \int_{-H}^H \int_0^{2\pi} \int_0^{r_{max}} r^3 \, dr \, d\theta \, dz$$

$$I_3 = \frac{\pi\rho R^4 H (15c^4 + 3H^4 + 10c^2H^2)}{15(c^2 + H^2)^2}$$

$$I_3 = \frac{MR^2 (15c^4 + 3H^4 + 10c^2H^2)}{10(3c^2 + H^2)(c^2 + H^2)}$$

en remplaçant ρ par son expression (3.5)

3.8

$c = 0 \rightarrow I_3 = \frac{3}{10} MR^2$

I_3 d'un cône, vu en cours

$c \rightarrow +\infty \rightarrow I_3 \rightarrow \frac{MR^2}{2}$

I_3 d'un cylindre