## Final Exam - January, the 16th 2015

Exercise 1 State and prove the pythagorean theorem in an inner product space.

- **Exercise 2** State the theorem of convergence of  $\mathcal{P}$ -series<sup>1</sup> and prove it.
- **Exercise 3** Study the convergence of the series  $\sum \ln(1 + \frac{1}{n^2})$ .

**Exercise 4** We consider the function f defined on  $\mathbb{R}$  by

$$f(x) = \frac{\pi - x}{2} \text{ for } x \in ]0, \ 2\pi[, \ f(0) = 0 \tag{1}$$

and extended by  $2\pi$ -periodicity.

- 1. Plot the graph of f in the interval  $[-2\pi, 4\pi]$ . This function is called the sawtooth wave<sup>2</sup>.
- 2. State the general form of the Fourier series of a T-periodic function f together with the expression of its coefficients  $a_n$  and  $b_n$ .
- 3. We denote by  $a_n$  and  $b_n$  the Fourier coefficients of f.
  - (a) Justify that  $a_n = 0$  for all  $n \neq 0$ .
  - (b) Admitting that  $\int_0^{2\pi} x \sin(nx) dx = -\frac{2\pi}{n}$  for all  $n \in \mathbb{N}^*$ . Calculate the coefficient  $b_n$ .
- 4. Prove the pointwise<sup>3</sup> convergence of the Fourier series of f.

**Exercise 5** We approximate the sawtooth wave (1) by a linear combination of the three trigonometric polynomials

$$\phi_0(x) = 1, \ \phi_1(x) = \sqrt{2}\sin x \ \text{and} \ \phi_2(x) = \sqrt{2}\sin(2x)$$

belonging to the Fourier basis of  $2\pi$ -periodic functions. We recall that this family is orthonormal for the inner product

$$\langle f,g \rangle = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x)g(x) \ dx.$$

We define the inner product space  $\mathcal{V}$  spanned by these trigonometric polynomials.

- 1. Calculate the orthogonal projection of the function f defined in (1) on the vector space  $\mathcal{V}$ . You may use the result of Exercise 4 question 3.
- 2. Let  $d(f, \mathcal{V})$  the distance between the function f and the vector space  $\mathcal{V}$ .
  - (a) Find the expression of  $d(f, \mathcal{V})$ .
  - (b) Calculate this distance.

<sup>&</sup>lt;sup>1</sup>also called Riemann series <sup>2</sup>onde en dents de scie.

<sup>&</sup>lt;sup>3</sup>ie at any  $x \in \mathbb{R}$ 

**Exercise 6** Let us denote by  $\mathcal{B}_0 = (e_1, e_2, e_3)$  the canonical basis of the vector space  $\mathbb{R}^3$ . We consider the matrix

$$A = \frac{1}{3} \begin{pmatrix} 2 & -1 & 2\\ 2 & 2 & -1\\ -1 & 2 & 2 \end{pmatrix} \in \mathfrak{M}_3(\mathbb{R}).$$

- 1. Verify that A is an orthogonal matrix.
- Determine the invariant space D of A.
  In the following, we denote by P the orthogonal projection on D.
- 3. Give, without justification, the kernel and the image of  $\mathcal{P}$ .
- 4. Find the matrix B of  $\mathcal{P}$  in the basis  $\mathcal{B}_0$ . Let f be the linear mapping in  $\mathbb{R}^3$  associated to the matrix A in the basis  $\mathcal{B}_0$ .
- 5. Prove that f is a rotation and find a vector n of the rotation axis.
- 6. Let  $\alpha$  be the rotation angle of f.
  - (a) Calculate  $\cos(\alpha)$ .
  - (b) Calculate  $\sin(\alpha)$ .
  - (c) Deduce the value of  $\alpha$ .